



Simulation-Based MDP Verification for Leading Edge Masks

Bo Su, Oleg Syrel, Michael Pomerantsev, Kazuyuki Hagiwara, Ryan Pearman, Leo Pang and Aki Fujimura

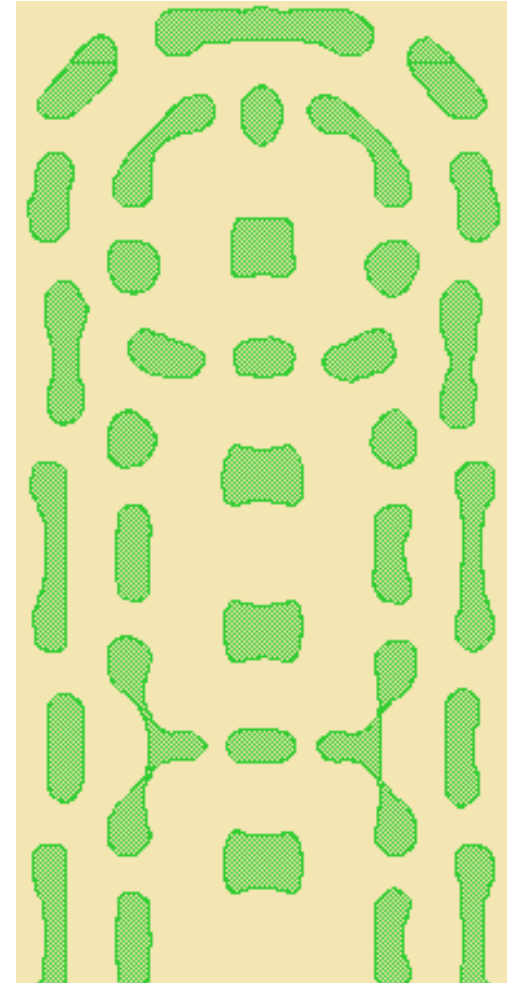
D2S Patented Technology

D2S is a registered trademark of D2S, Inc. in US

TrueMask® and TrueModel® are registered trademarks of D2S, Inc. in US, Japan, Korea, China and Taiwan

GPU Accelerates Processing Complex Curvilinear Shapes

- Curvilinear mask shapes no longer can be ignored
- Verifying curvilinear mask shapes requires massive computation
- GPUs can accelerate processing of complex curvilinear shapes:
 - Created massively parallel versions of classic computational geometry algorithms;
 - Confirmed >10x speedup with GPU Acceleration
- GPU makes simulation-based MDP verification possible
 - Accurate physical mask model
 - GPU is required for simulation with overlapped shots and dose modulation

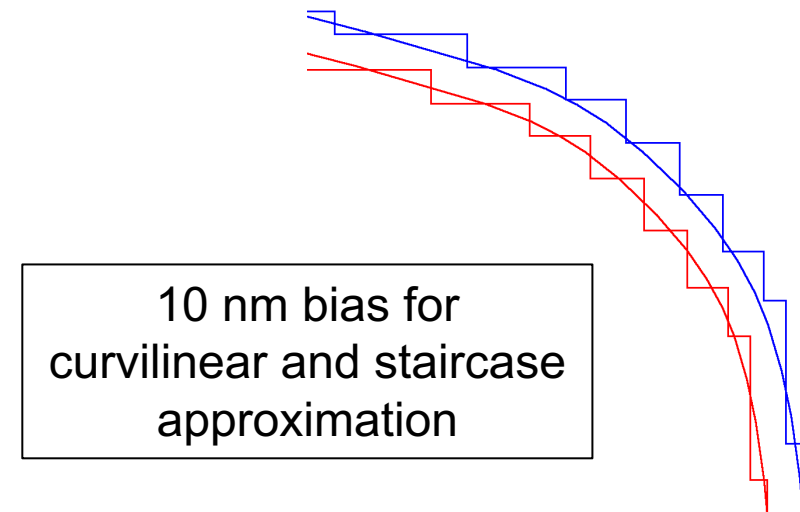
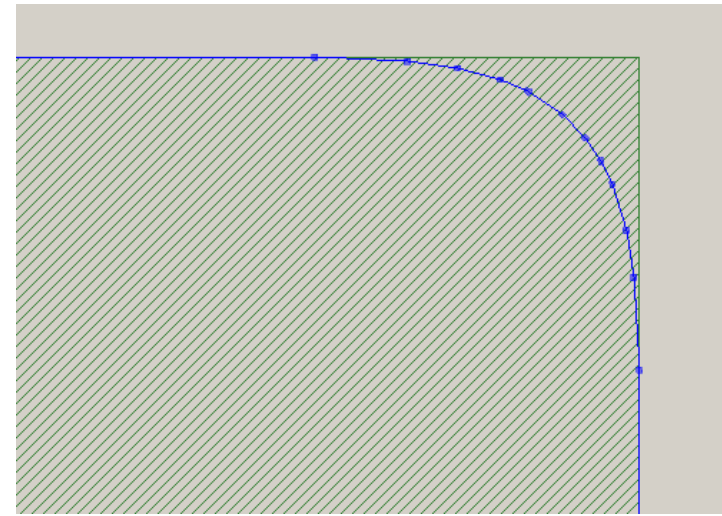


Shapes on Masks are all Curvilinear

- Regardless of OPC styles for mask writing:
 - Simulated mask shapes are curvilinear
 - Mask shapes from SEM images are curvilinear
 - Design can be curvilinear for ILT
- Curvilinear shapes consist of many little segments ***at all angles with significant complexity increase***
- GPU accelerates curvilinear processing

Curvilinear Shapes Require Complex Geometry Algorithms

- Curvilinear shapes, geometry representation is much more complex:
 - Segment by segment at nm scale at all angles
- Higher requirement for robustness and complex algorithms
 - Staircase approximation is not good for etch bias—average 20% error for a rounded corner
 - direct curvilinear bias is more accurate



10 nm bias for
curvilinear and staircase
approximation

Mask Verification Needs Massive Computation

One example:

- Simulation to obtain mask contour from shots—The AEI contour generated, up to a full mask scale
- Etch Bias is calculated along the AEI curvilinear contour at every sampling point, using ***visible open area (VOA) calculation*** to approximate surrounding feature impact within search distance to get the corresponding ADI contour
- GPU-accelerated geometry engine for contour analysis with geometric algorithms

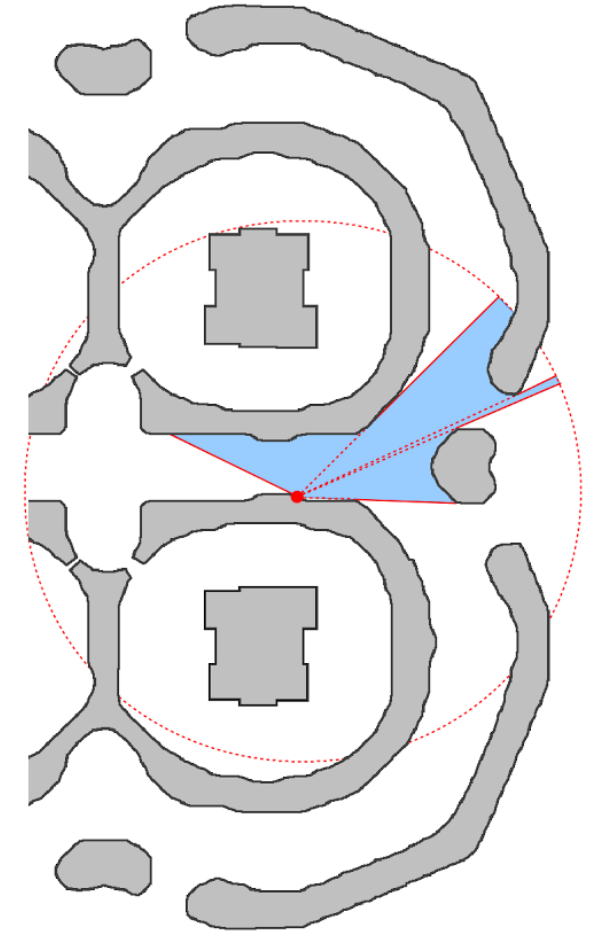
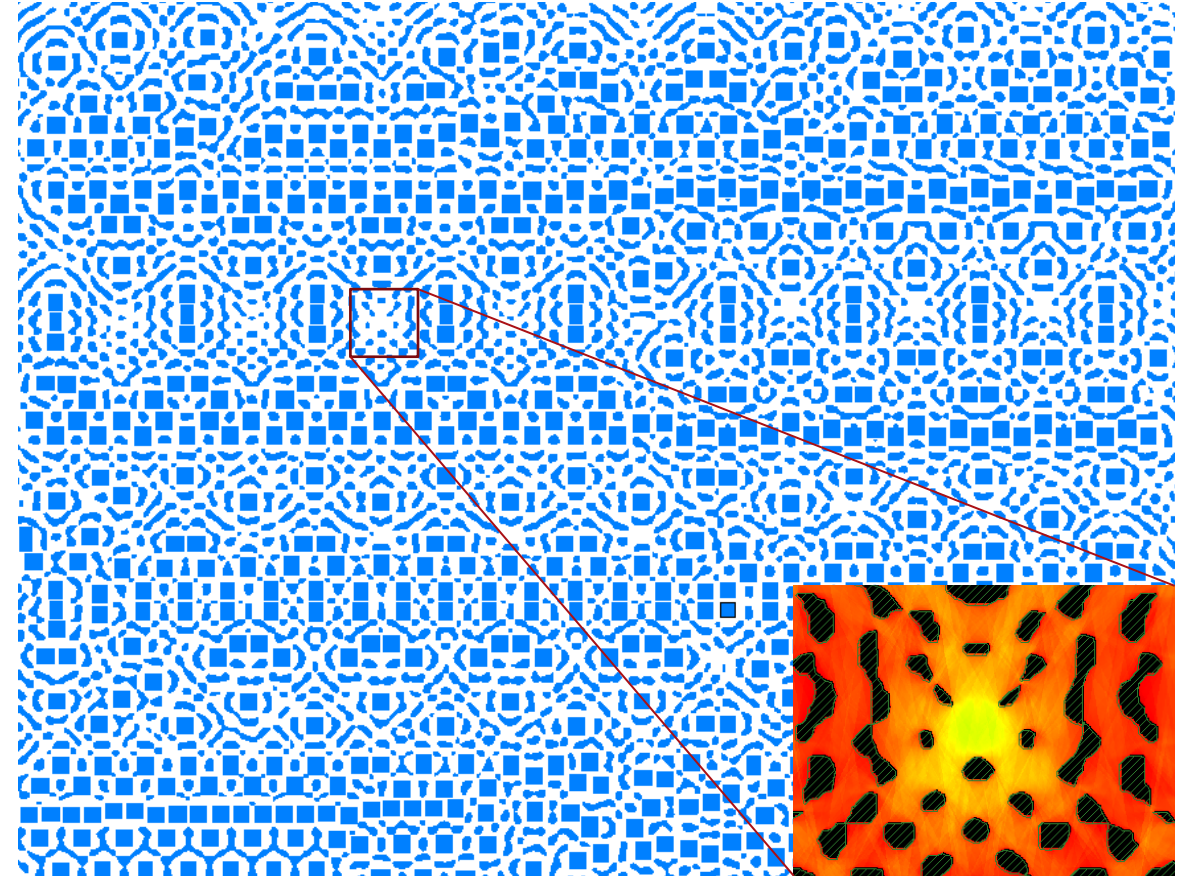


Illustration of VOA calculation at a given point

Case Study: GPU Faster Than CPU in Bulk VOA Calculation

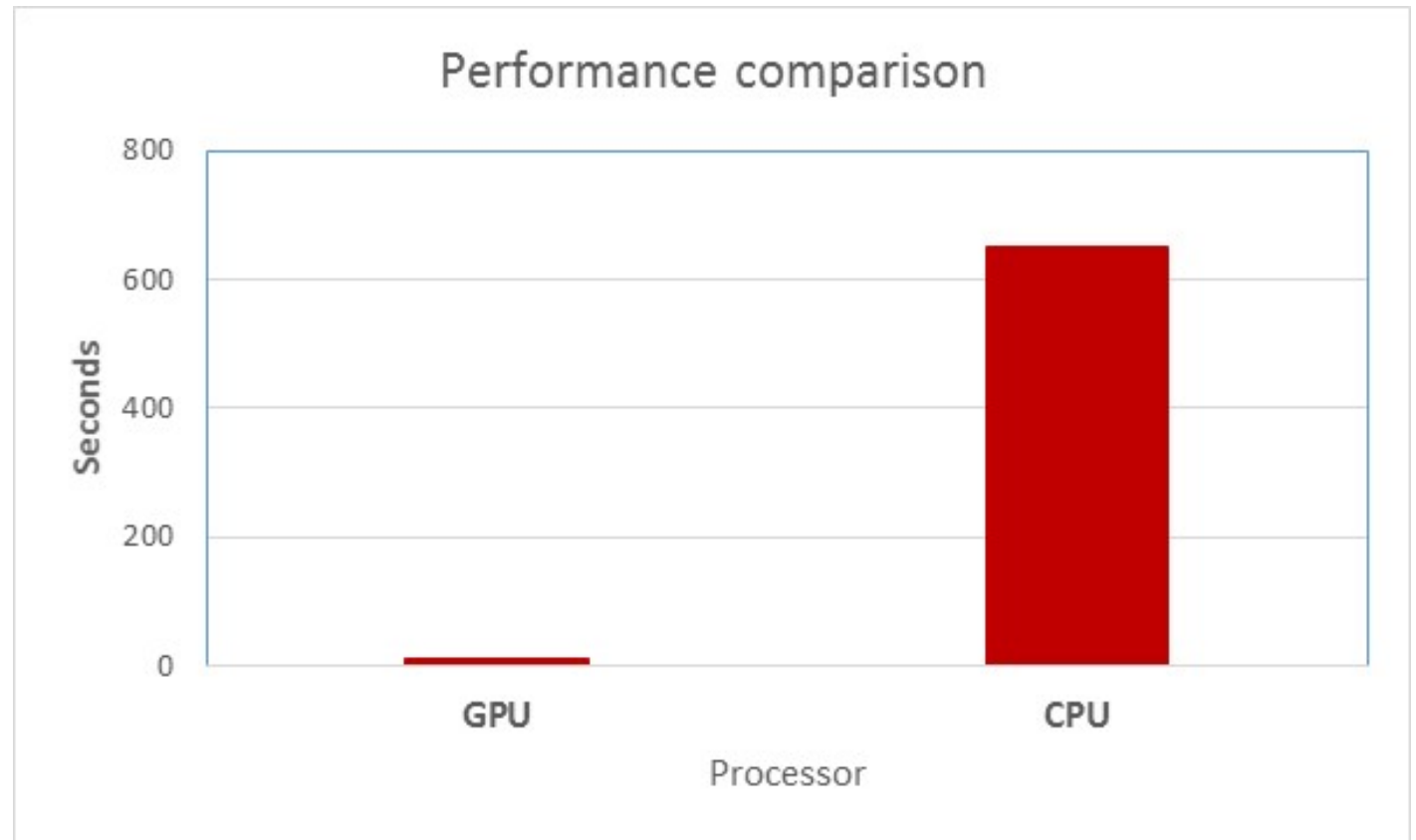
- GPU vs. CPU on **visible open area (VOA)** calculation:
 - Test case—**Manhattanized ILT**, 28x21um with *4nm sampling size* and 700nm search distance (Not realistic usage)
 - GPU=GeForce GTX 1080
 - CPU=4 core Intel Xeon E3-1220 v5 @ 3.00GHz



VOA zoom-in view
in color code

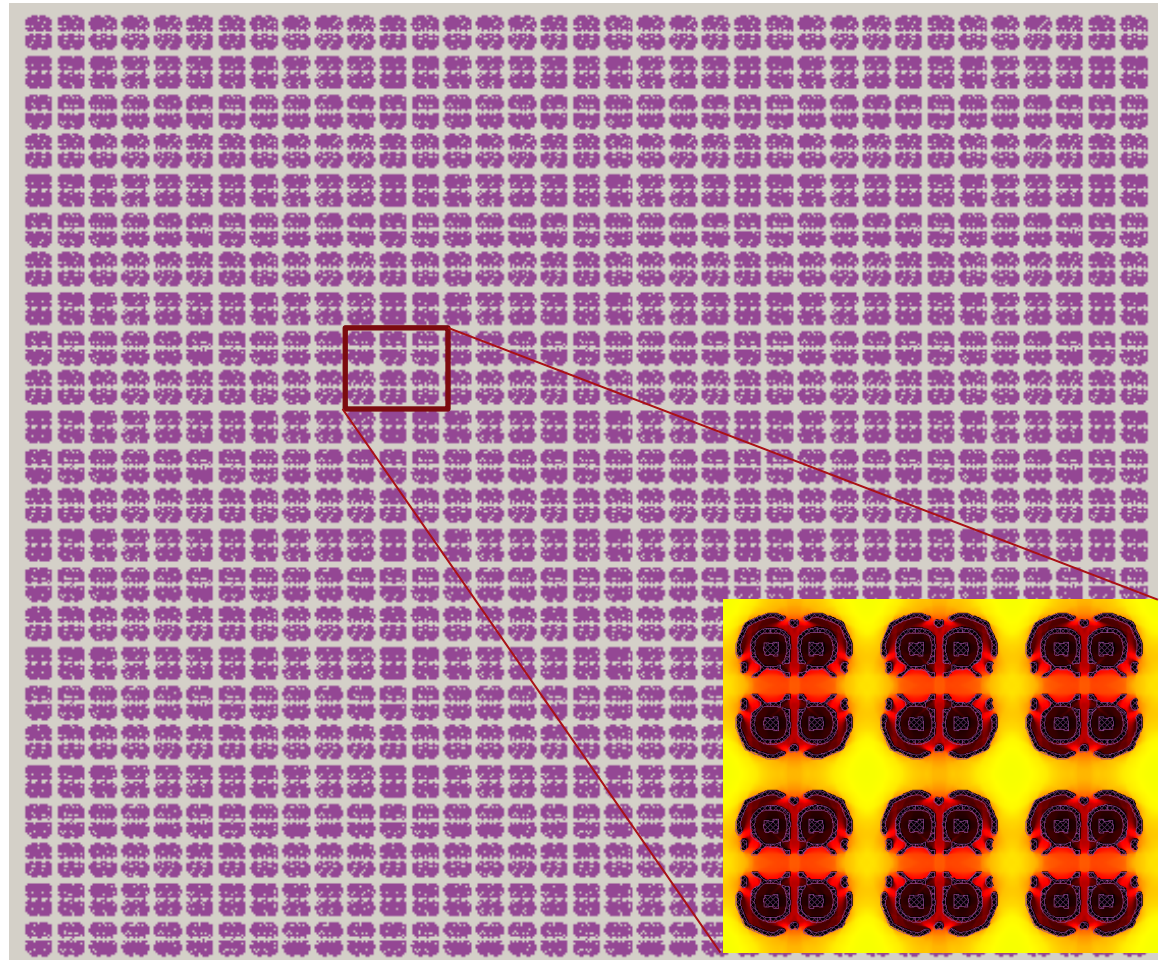
Test 1 Shows GPU is 54x Faster Than CPU

- With 4nm step size and 700nm search range:
 - GPU=12 seconds
 - CPU=650 seconds
- GPU is 54x faster than CPU



GPU vs. CPU in Test Case 2—ILT Design

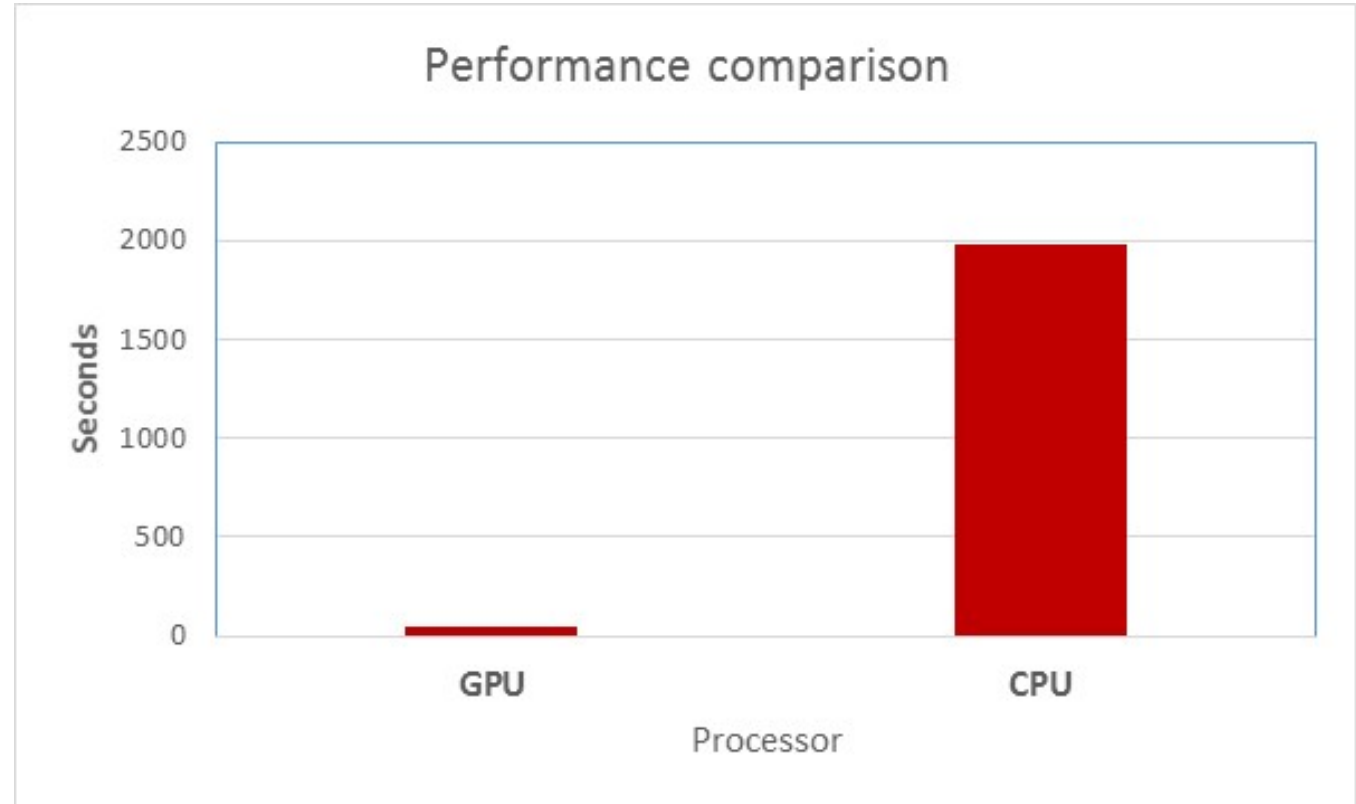
- GPU vs. CPU on **visible open area calculation** on a curvilinear ILT:
 - Test case—ILT design, 31x26um with 4nm sampling size and 500nm search distance
 - GPU=GeForce GTX 1080
 - CPU=4 core Intel Xeon E3-1220 v5 @ 3.00GHz



VOA zoom-in view
in color code

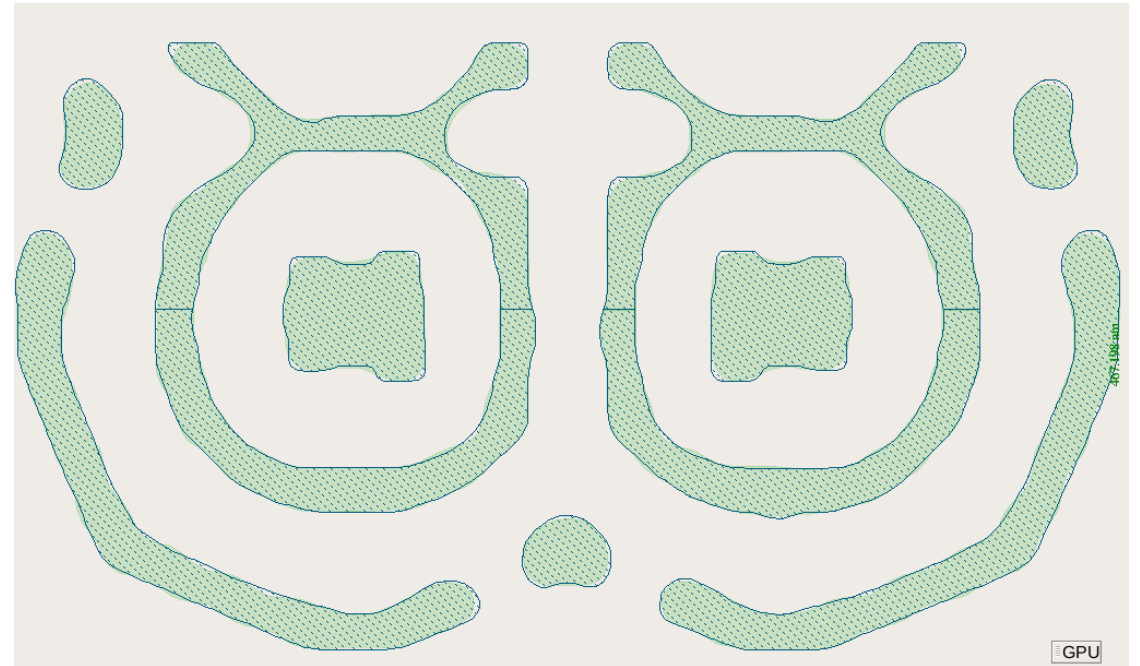
Test Case 2 Shows GPU is 44x Faster Than CPU

- With 4nm step size and 500nm search range:
 - GPU=45 seconds
 - CPU=1980 seconds
- GPU is 44x faster than CPU



GPU vs. CPU in Contour Simulation—Real Apps

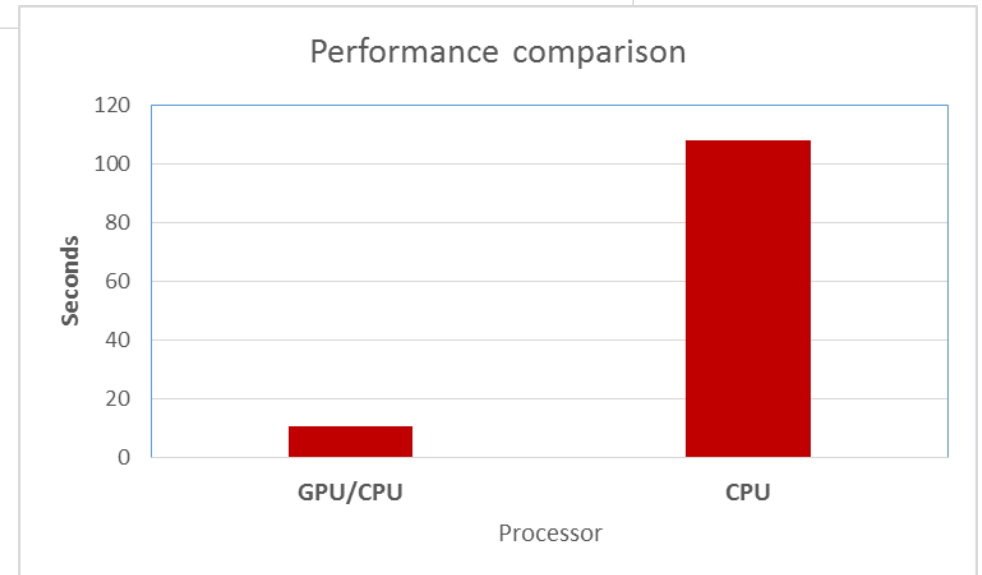
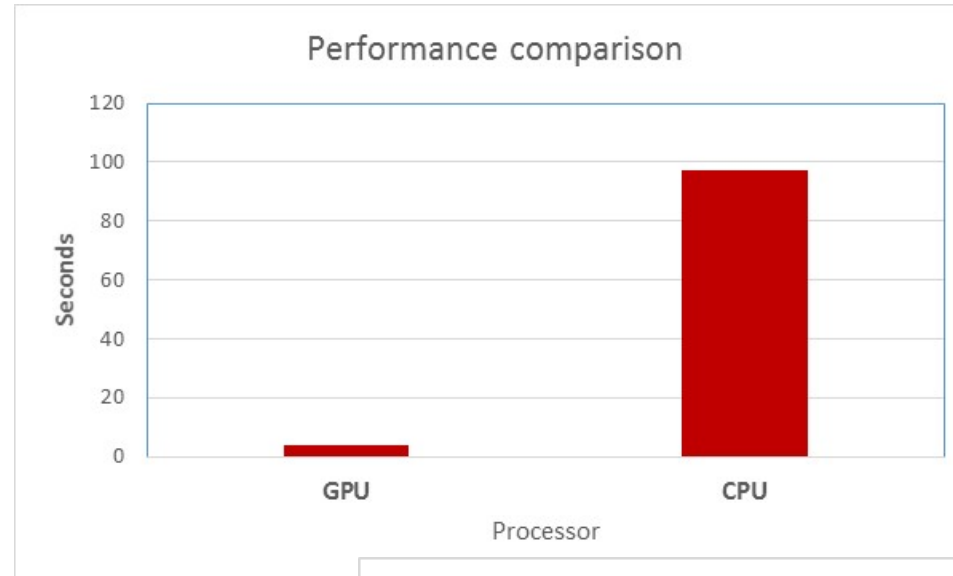
- GPU vs. CPU in real contour simulation, same as Test 2:
 - With a real mask model
 - 31x26um
 - GPU=GeForce GTX 1080
 - CPU=4 core Intel Xeon E3-1220 v5 @ 3.00GHz
- **In more accurate simulation mode, as shown**



Simulated contour in more accurate mode

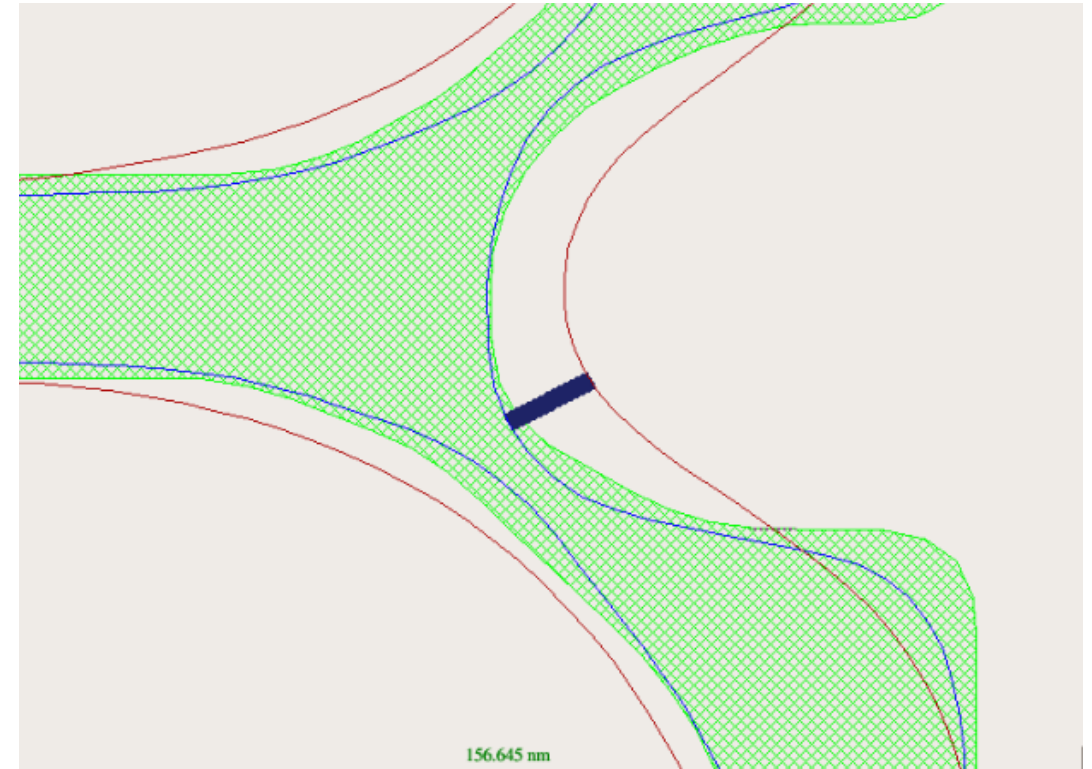
GPU+CPU is 10x Faster Than CPU in Etch Bias Simulation

- In contour simulation—in geometry calculation only:
 - GPU=4 seconds
 - CPU=97 seconds
- Considering everything else (all other steps):
 - GPU+CPU=11 seconds
 - CPU=108 seconds



Simulation-Based MDP Verification Engine was Developed

- GPU-accelerated simulation engine
- Curvilinear geometry analysis
 - EPEs in 1D and 2D regions—EPEs between two curvilinear contours: the target and the mask
 - Dose margin check (hotspot detection)—flag regions with large EPE change with a fixed dose variation



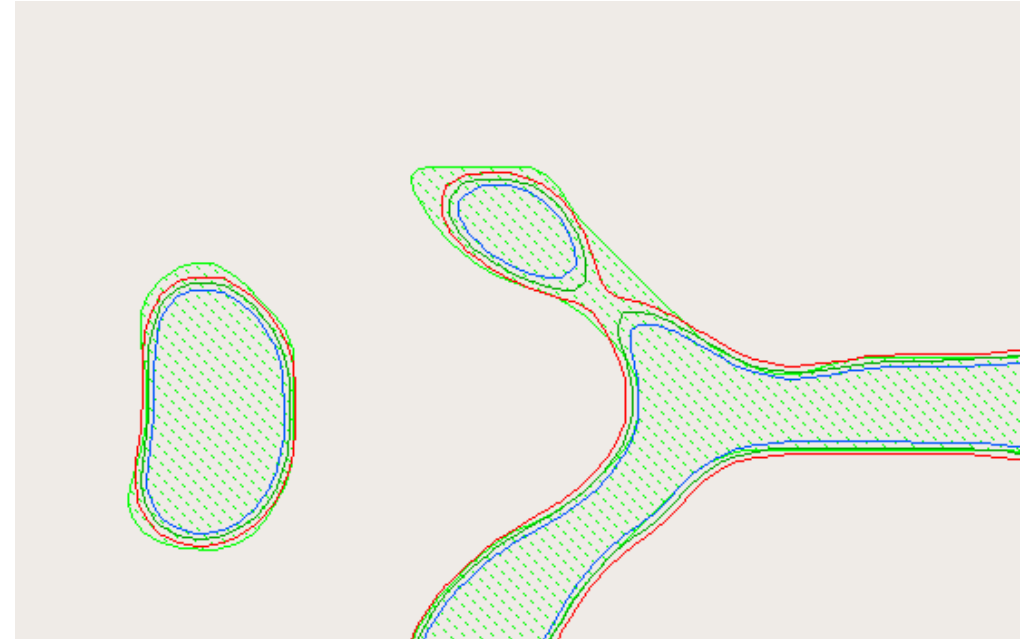
An example of a 2D EPE error.

Real Simulation-Based Verification Runs...

- Layout area=14.2mm² (M), ILT style design

- Runtime:

Phase	Time
Import	0d:00:00:26
Verification	0d:00:10:04
Total	0d:00:10:30



- Translates to <4 hours for 48x48mm² mask scale on 5th Generation CDP

GPU is Good for Curvilinear Shape Processing

- Mask shapes are curvilinear and GPU accelerates curvilinear shape processing
- Our visible open area calculation tests show that GPU is 50x faster than CPU in curvilinear geometry shapes
- In etch bias simulation case, GPU+CPU is 10x faster than CPU
- GPU acceleration enables simulation-based mask verification
 - provides a quality check for MB-MDP

